**Daily Scrum Meeting Minutes:**

Attendees: Artem Andrianov, Mojeed Oladele Ashaleye, Amanda Beatriz Chacin-Livinalli, Noah C Cuevas, Max Samuel Karey

Start time: 4:00 PM

End time: 4:30 PM

Artem Andrianov

* How many hours have I worked since the last meeting?
  + 2
* What was done since the last scrum meeting?
  + Provided additional measurements Dr. Chen requested. Reviewed and revised Amanda’s email template. Dr, Chen said he would 3D print the camera mount for the microscope.
* What is planned to be done until the next scrum meeting?
  + Send out email to additional researchers and review openCV python articles the rest of the team found
* What are the hurdles?
  + None yet.

Mojeed Oladele Ashaleye

* How many hours have I worked since the last meeting?
  + 2
* What was done since the last scrum meeting?
  + Found an additional researcher for Amanda to email
  + Read up on algae data sets
* What is planned to be done until the next scrum meeting?
  + Use of the ESP32 camera and data collection
* What are the hurdles?
  + None so far

Amanda Beatriz Chacin-Livinalli

* How many hours have I worked since the last meeting?
  + 2
* What was done since the last scrum meeting?
  + Finished drafting email template
  + Emailed selected researchers
* What is planned to be done until the next scrum meeting?
  + Review overall team progress
* What are the hurdles?
  + N/A

Noah C Cuevas

* How many hours have I worked since the last meeting?
  + 2 hours
* What was done since the last scrum meeting?
  + Research on how to pair the ESP32 camera with software for image processing
* What is planned to be done until the next scrum meeting?
  + Continue researching hard and software comparison
* What are the hurdles?
  + No hurdles

Max Samuel Karey

* How many hours have I worked since the last meeting?
  + 2
* What was done since the last scrum meeting?
  + Researched camera hardware associated with ESP32 camera and how python can get the data.
* What is planned to be done until the next scrum meeting?
  + Continue to research Integration for ESP32 camera and Python integration
* What are the hurdles?
  + None